

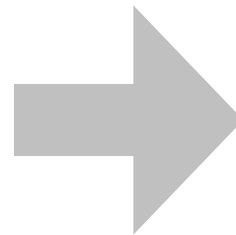
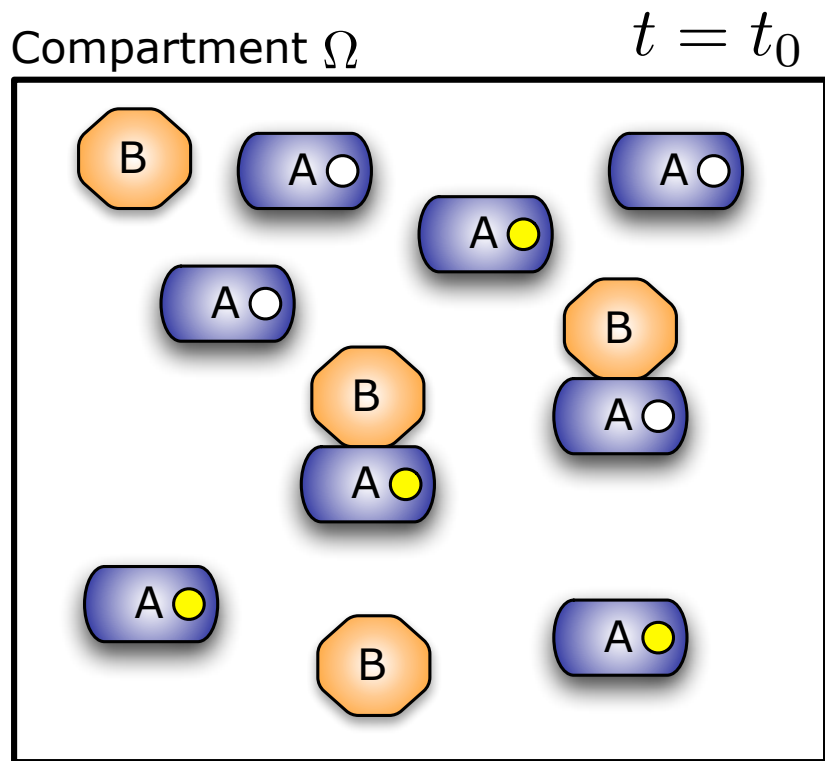
Accounting for Extrinsic Variability in the Estimation of Stochastic Rate Constants

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Switzerland

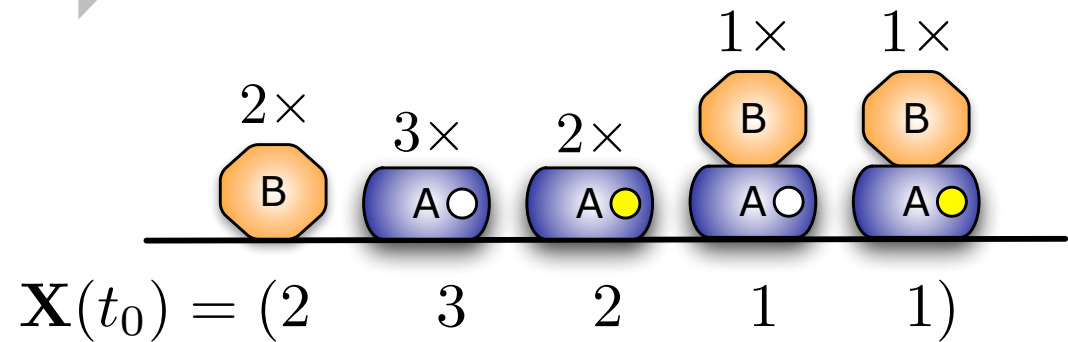
...joint work with

*C. Zechner (ALC/ETHZ)
Arnab Ganguly (ALC/ETHZ)
Serge Pelet (IBC/ETHZ)
Matthias Peter (IBC/ETHZ)*

- Modeling chemical kinetics by a CTMC
- Cell-to-cell variability - extrinsic noise
- Statistical inference - recursive estimation scheme
- Modeling case study: osmo-stress response in yeast
- Conclusions

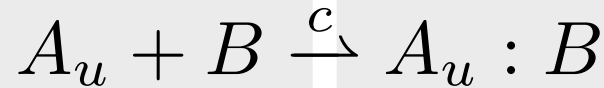
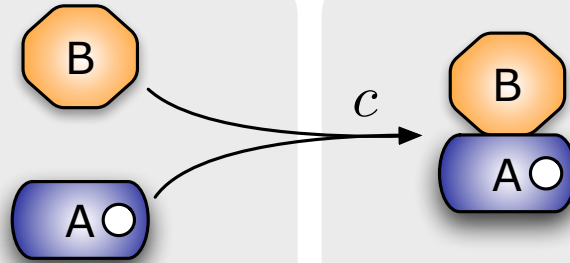


Population encoding

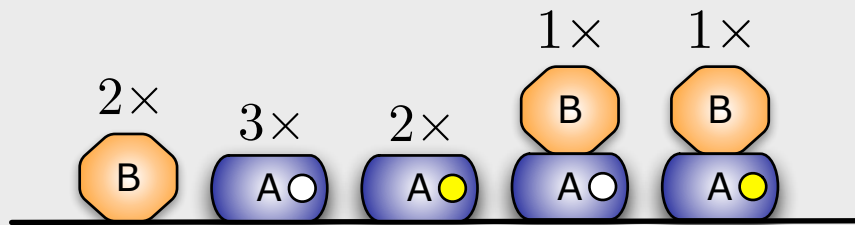


state vector of species multiplicity

Species transformations: reactions

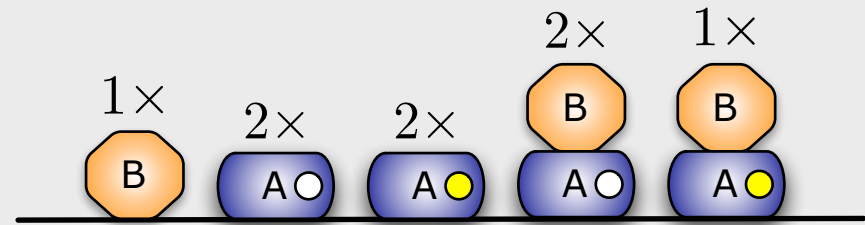


Population state at t



$$\mathbf{X}(t) = (2 \quad 3 \quad 2 \quad 1 \quad 1)$$

Population state at $t + \Delta$



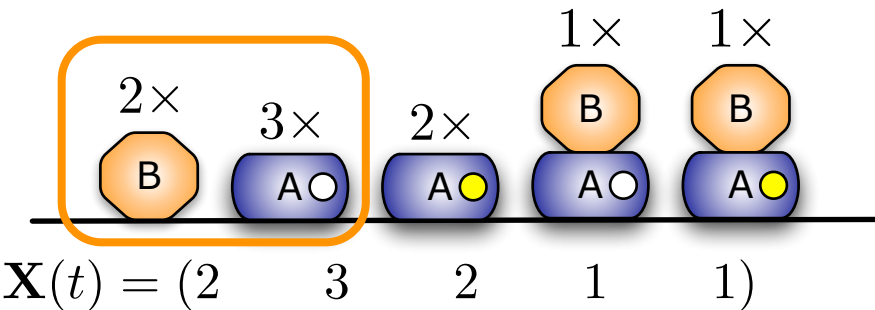
$$\mathbf{X}(t + \Delta) = (1 \quad 2 \quad 2 \quad 2 \quad 1)$$

$$\delta = (-1 \quad -1 \quad 0 \quad 1 \quad 0)$$

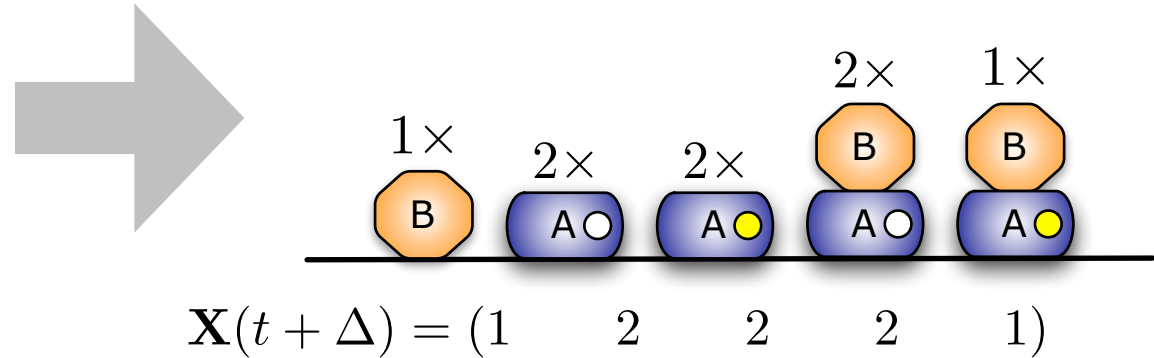
state-change vector of reaction

State-dynamics: Continuous-time Markov chain (CTMC)

Population state at t



Population state at $t + \Delta$



Propensity or intensity of reaction/jump

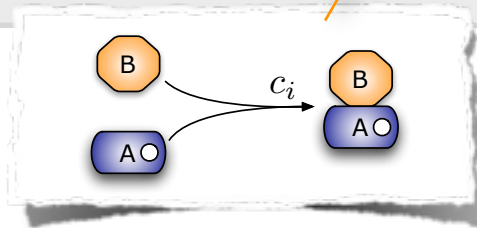
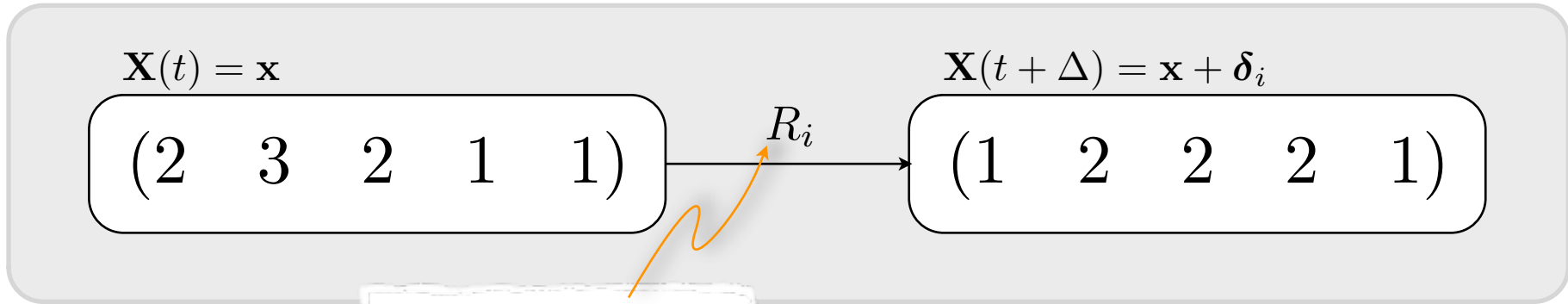
$$\begin{aligned}
 P[\mathbf{X}(t + \Delta) = \mathbf{x} + \boldsymbol{\delta} \mid \mathbf{X}(t) = \mathbf{x}] &= a(\mathbf{x})\Delta + o(\Delta) \\
 &= c \cdot x_1 x_2 \Delta + o(\Delta) \\
 &= c \cdot 2 \cdot 3 \Delta + o(\Delta)
 \end{aligned}$$

Transition probability of a continuous-time Markov chain

In how many ways B and Au can combine?

$$f(\Delta) \in o(\Delta) \quad \text{if} \quad \lim_{\Delta \rightarrow 0} \frac{f(\Delta)}{\Delta} = 0$$

Properties of a continuous-time Markov chain



Jump times

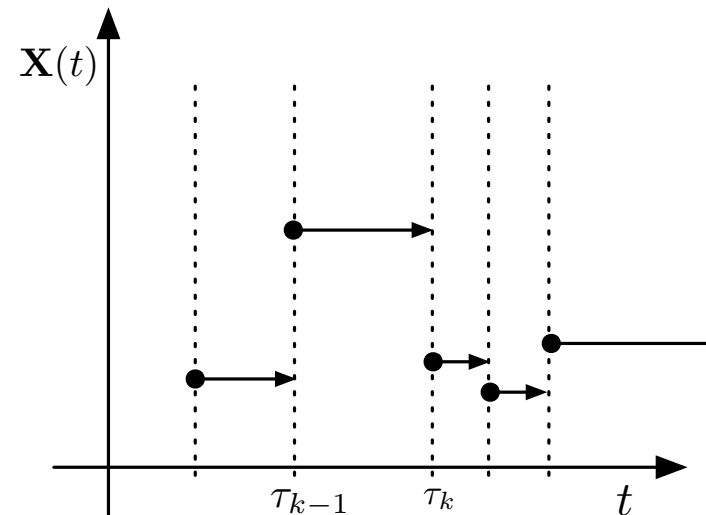
$$\tau_k = \inf\{s > \tau_{k-1} | \mathbf{X}(s) \neq \mathbf{X}(\tau_{k-1})\}$$

Waiting times

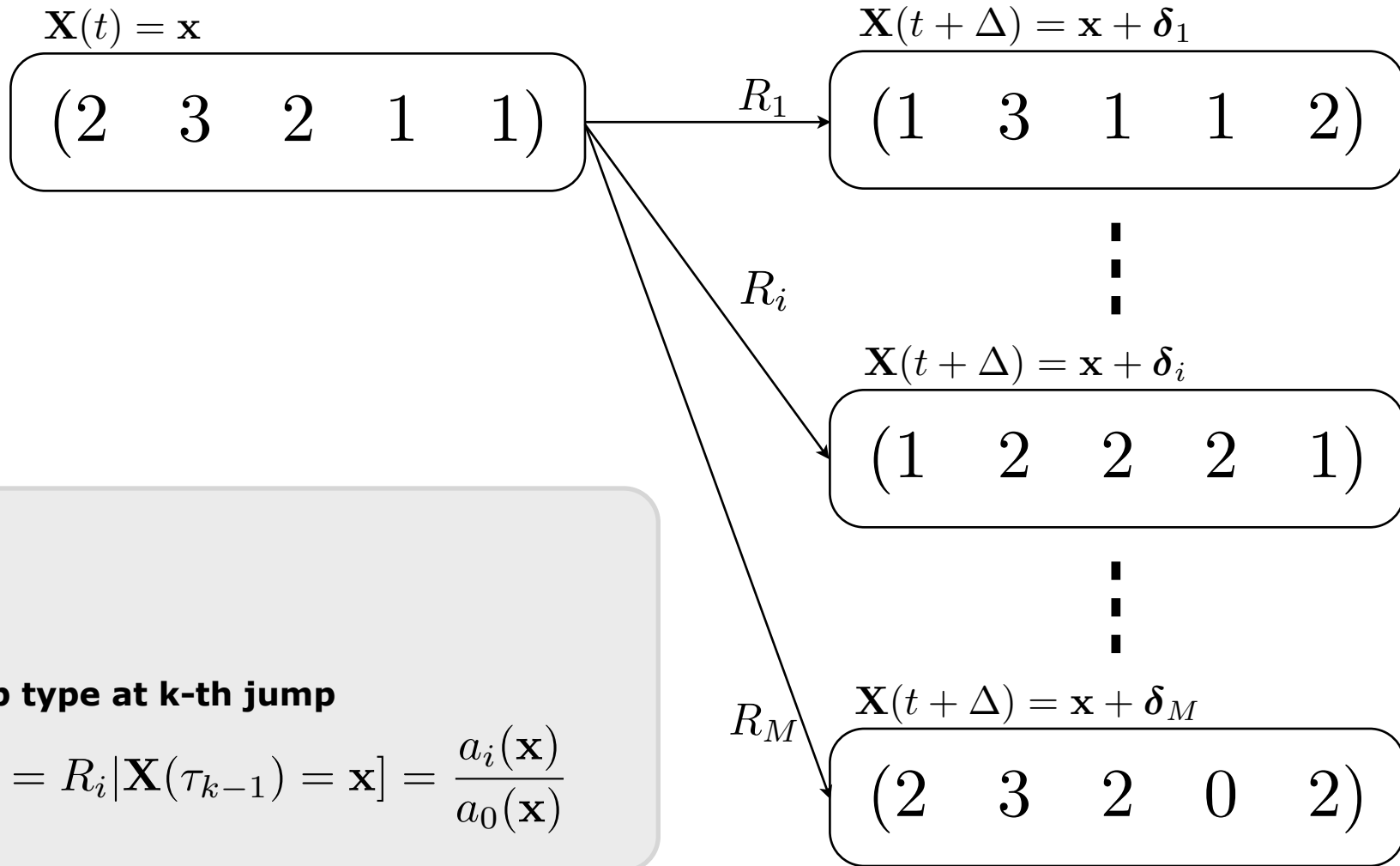
$$(\tau_k - \tau_{k-1} | \mathbf{X}(\tau_{k-1}) = \mathbf{x}) \sim \text{Exp}\{a_0(\mathbf{x})\}$$

Total intensity

$$a_0(\mathbf{x}) = a_1(\mathbf{x}) + \dots + a_M(\mathbf{x})$$



Properties of a continuous-time Markov chain: jump type

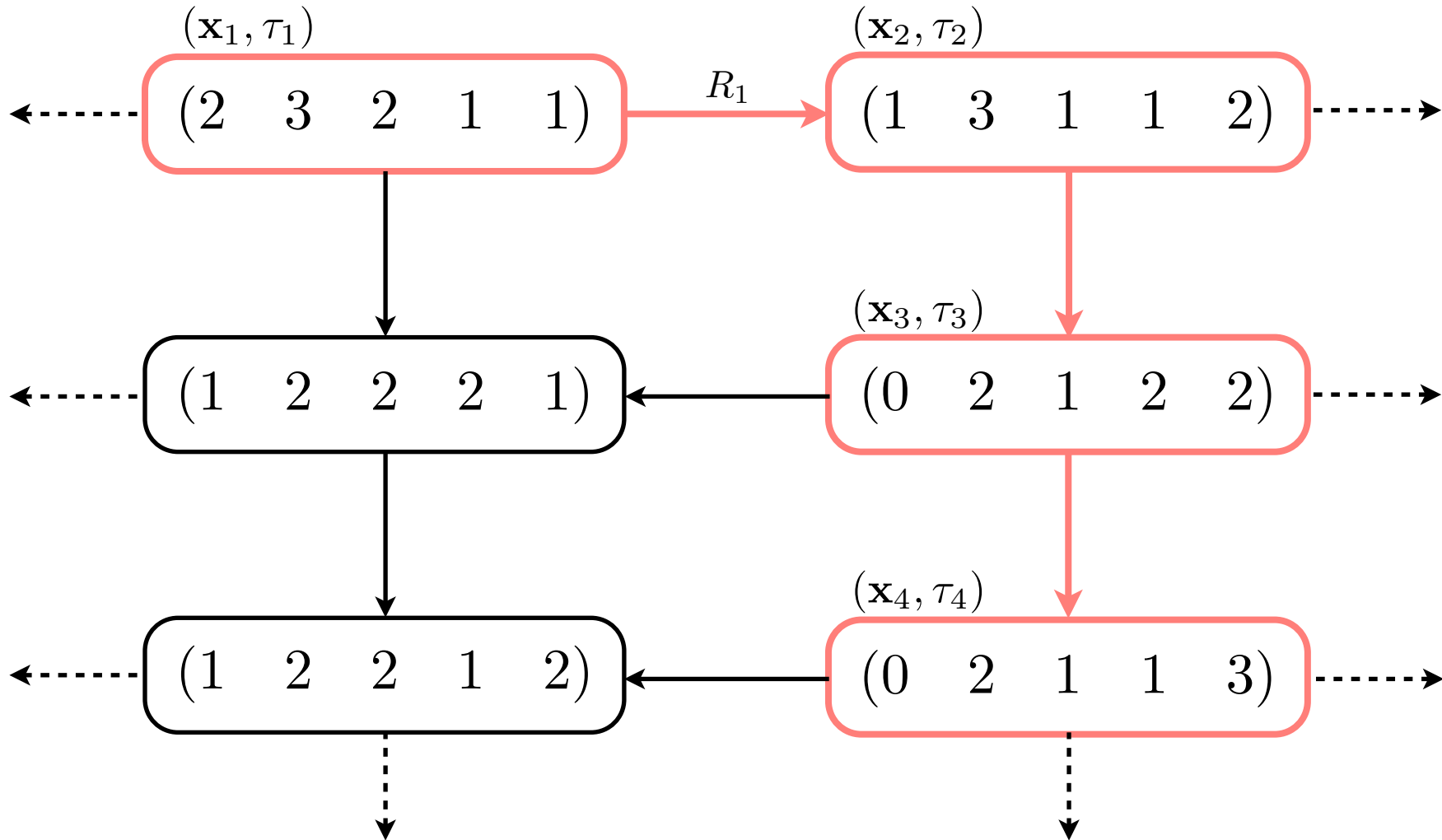


Jump type at k-th jump

$$P[r_k = R_i | \mathbf{X}(\tau_{k-1}) = \mathbf{x}] = \frac{a_i(\mathbf{x})}{a_0(\mathbf{x})}$$

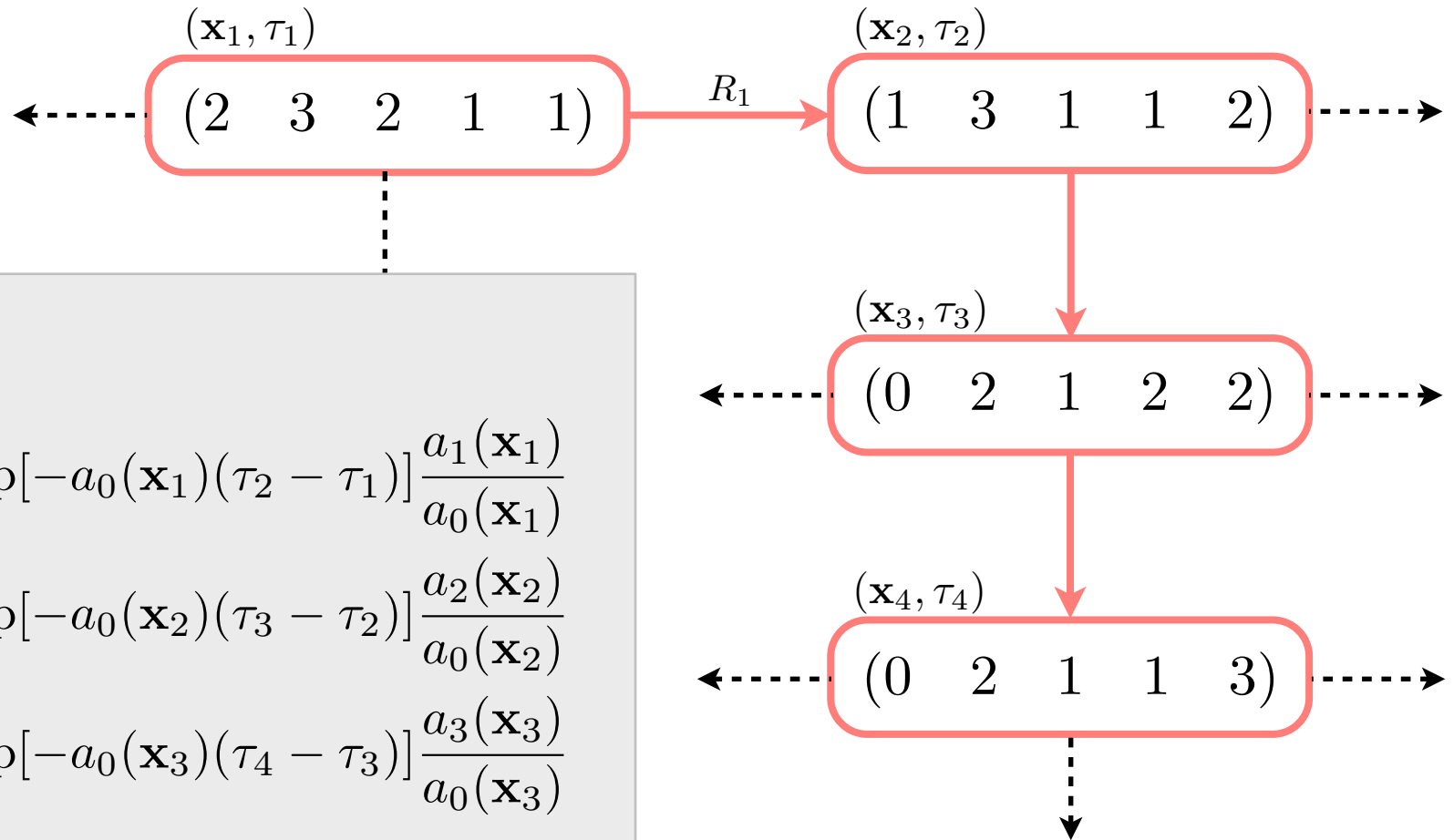
○ A sample path and its density

■ Observe a sample path (through the transition system)



■ Density of path

$$\pi = (\mathbf{X}_{[\tau_1, \tau_4]} = \mathbf{x}_{[\tau_1, \tau_4]}) = \{(\mathbf{x}_1, \tau_1), (\mathbf{x}_2, \tau_2), (\mathbf{x}_3, \tau_3), (\mathbf{x}_4, \tau_4)\}$$

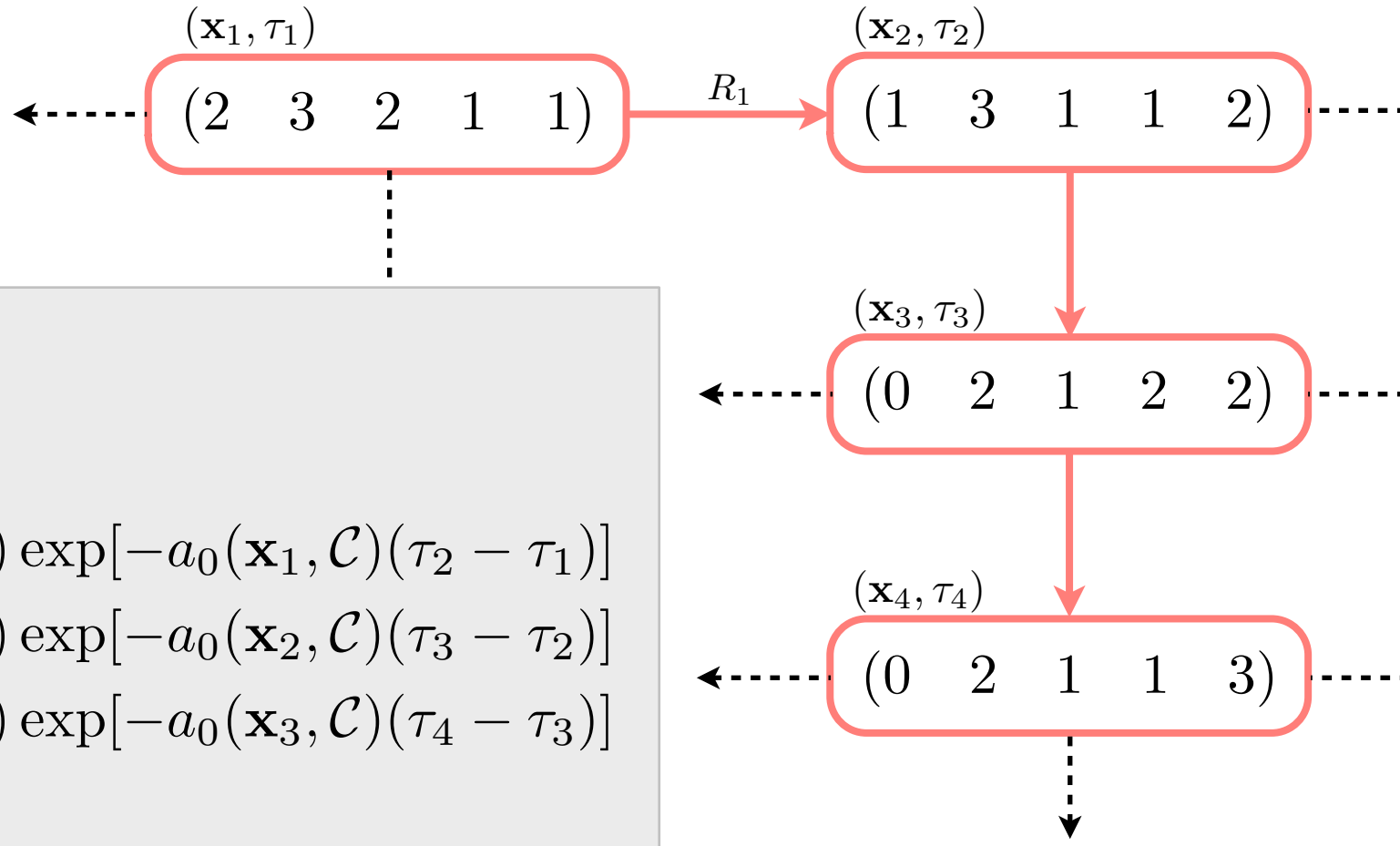


$$\begin{aligned}
 p(\pi) &= p(\mathbf{x}_1) \\
 &\times a_0(\mathbf{x}_1) \exp[-a_0(\mathbf{x}_1)(\tau_2 - \tau_1)] \frac{a_1(\mathbf{x}_1)}{a_0(\mathbf{x}_1)} \\
 &\times a_0(\mathbf{x}_2) \exp[-a_0(\mathbf{x}_2)(\tau_3 - \tau_2)] \frac{a_2(\mathbf{x}_2)}{a_0(\mathbf{x}_2)} \\
 &\times a_0(\mathbf{x}_3) \exp[-a_0(\mathbf{x}_3)(\tau_4 - \tau_3)] \frac{a_3(\mathbf{x}_3)}{a_0(\mathbf{x}_3)}
 \end{aligned}$$

○ A sample path and its density

■ Mass-action propensities $a_i(\mathbf{x}) = c_i f_i(\mathbf{x})$

monoms in \mathbf{x}



$$\begin{aligned}
 p(\pi|\mathcal{C}) = & p(\mathbf{x}_1) \\
 & \times c_1 f_1(\mathbf{x}_1) \exp[-a_0(\mathbf{x}_1, \mathcal{C})(\tau_2 - \tau_1)] \\
 & \times c_2 f_2(\mathbf{x}_2) \exp[-a_0(\mathbf{x}_2, \mathcal{C})(\tau_3 - \tau_2)] \\
 & \times c_3 f_3(\mathbf{x}_3) \exp[-a_0(\mathbf{x}_3, \mathcal{C})(\tau_4 - \tau_3)]
 \end{aligned}$$

General form of path density

Take a general path

$$\pi = (\mathbf{X}_{[\tau_1, \tau_J]} = \mathbf{x}_{[\tau_1, \tau_J]}) = \{(\mathbf{x}_1, \tau_1), \dots, (\mathbf{x}_J, \tau_J)\}$$

number of occurrences of reaction m in the path

$$p(\pi|\mathcal{C}) = p(\mathbf{x}_1) \left[\prod_{m=1}^M c_m^{r_m} \right] \left[\prod_{j=1}^J f_{m_j}(\mathbf{x}(\tau_j)) \right] \exp \left\{ - \int_{\tau_1}^{\tau_J} a_0(\mathbf{x}(s), \mathcal{C}) ds \right\}$$
$$\propto \left[\prod_{m=1}^M c_m^{r_m} \right] \exp \left\{ - \int_{\tau_1}^{\tau_J} a_0(\mathbf{x}(s), \mathcal{C}) ds \right\}$$

Factorization of density

$$p(\pi|\mathcal{C}) \propto g(\pi|\mathcal{C}) = \prod_{m=1}^M g_m(\pi|c_m)$$

Gamma distribution

$$\Gamma(a, b) \propto x^{a-1} e^{-bx}$$

$$g_m(\pi|c_m) = c_m^{r_m} \exp \left\{ -c_m \int_{\tau_1}^{\tau_J} f_m(\mathbf{x}(s)) ds \right\}$$

○ The posterior - density of parameter given a path

- Assume prior conjugate to path density (likelihood)

$$g_m(\pi | c_m) = c_m^{r_m} \exp \left\{ -c_m \int_{\tau_1}^{\tau_J} f_m(\mathbf{x}(s)) ds \right\}$$

- Independent Gamma priors $c_m \sim \Gamma(a_m, b_m)$

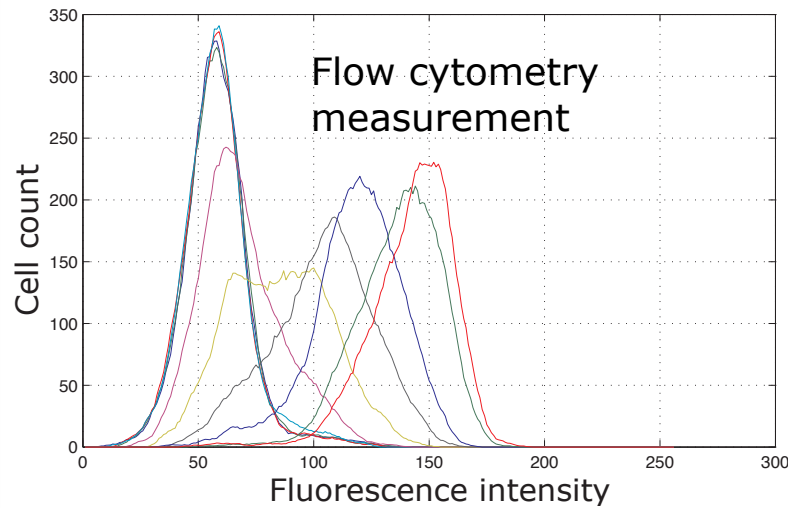
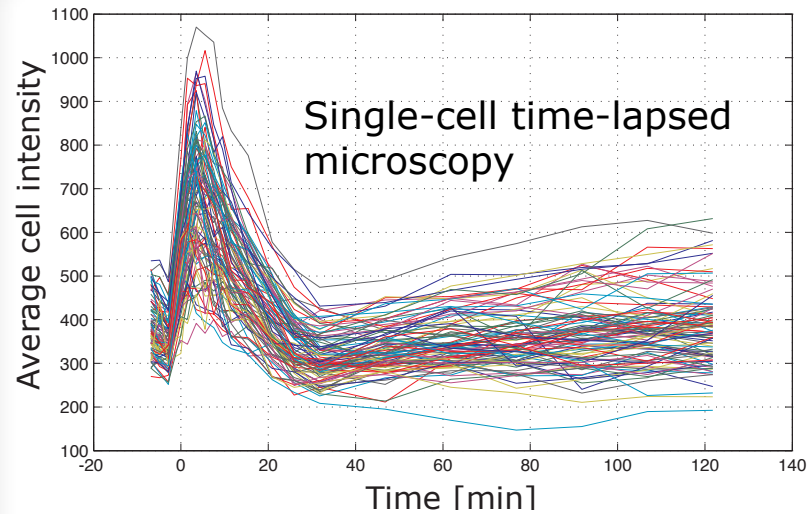
Posterior

$$c_m | \pi \sim \Gamma \left(a_m + r_m, b_m + \int_{\tau_1}^{\tau_J} f_m(\mathbf{x}(s)) ds \right)$$

- Given a sample path we can sample parameters and also compute MAP estimates.

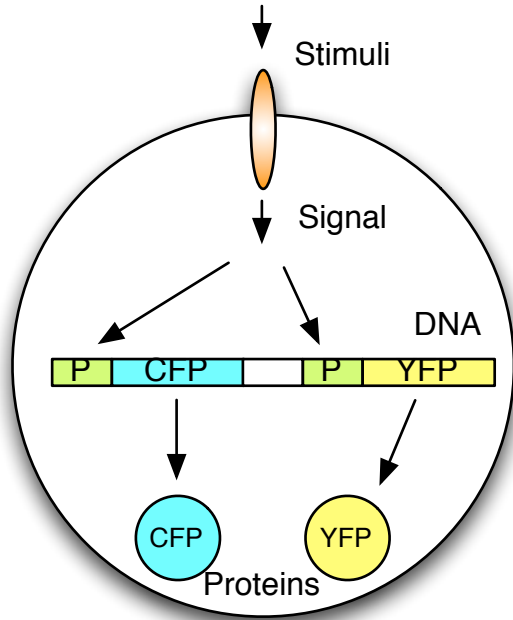
- Modeling chemical kinetics by a CTMC
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Variability in single-cell measurements

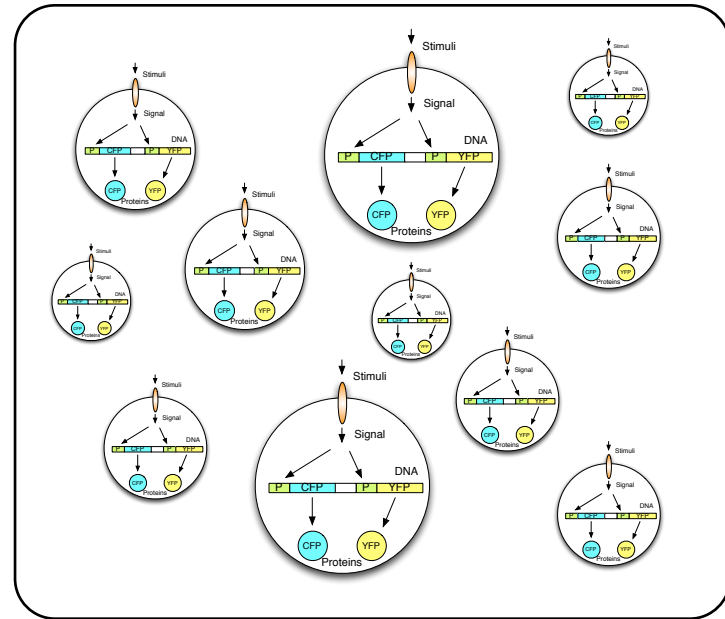


- New measurement technologies resolve protein dynamics at single cell level.
- Sources of cell-to-cell variability in isogenic cell population?
- Tempting to attribute variability solely to stochastic chemical kinetics.
- Large extrinsic components, volume, cell-cycle stage, concentration.

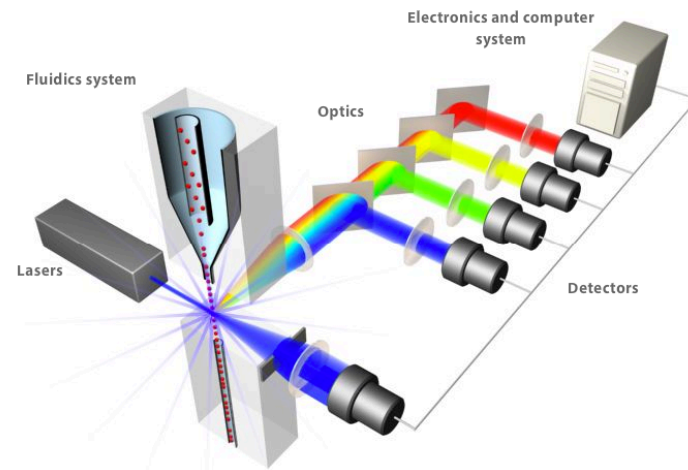
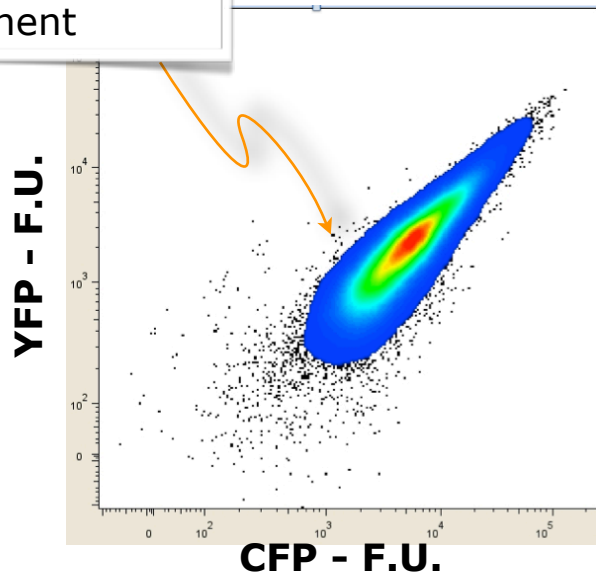
Engineered yeast strain



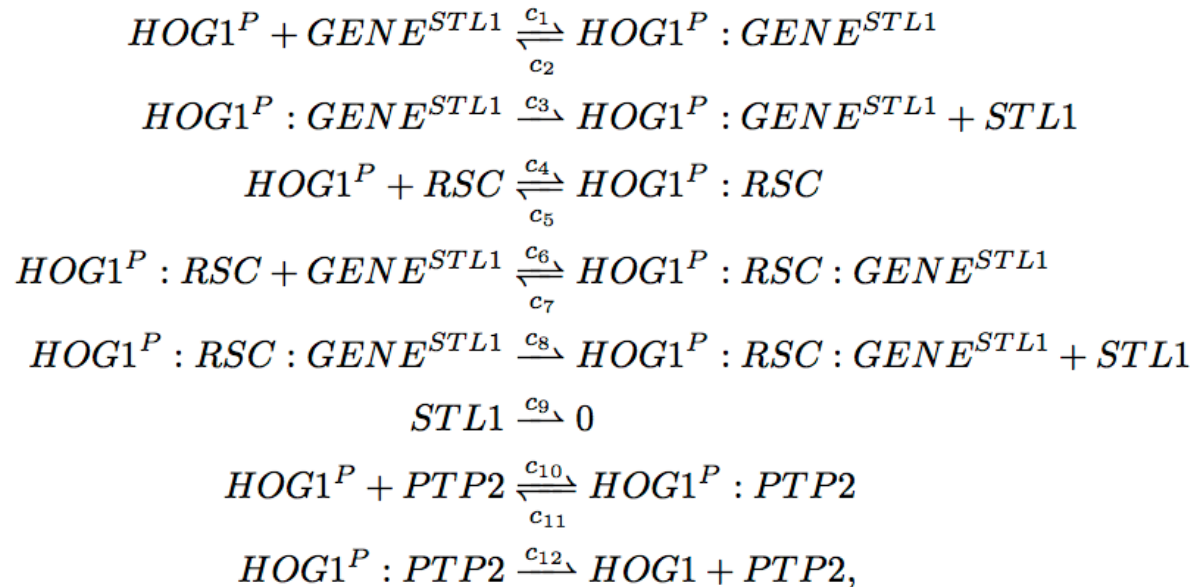
cell-population



Strong correlation - weaker stochastic component



Reaction list



Every cell corresponds to one realization of that process

Extrinsic components

$$dc_i(t) = \gamma(c_i^0 - c_i(t))dt + dW(t)$$

Ornstein-Uhlenbeck process for rate constants

- Rate constants **fluctuate independently** around same mean.
- Ignoring common **lower-dimensional causes** of cell-to-cell variability.
- Cannot account for **strong temporal correlation** to the cell-state (e.g. cell-cycle position).
- Mechanistic rate constants **determined by biophysics** of interacting molecules - should be invariant.

- Treat mechanistic **rate-constants as invariant** across of an isogenic cell population.
- Incorporate **variability in total protein count** and concentration, i.e. in mass-conservation constraints.
- For fast processes such as signaling, **temporal variation can be ignored.**
- Variability in protein count or concentration result in variability of **rate parameters in aggregated rate-laws.**

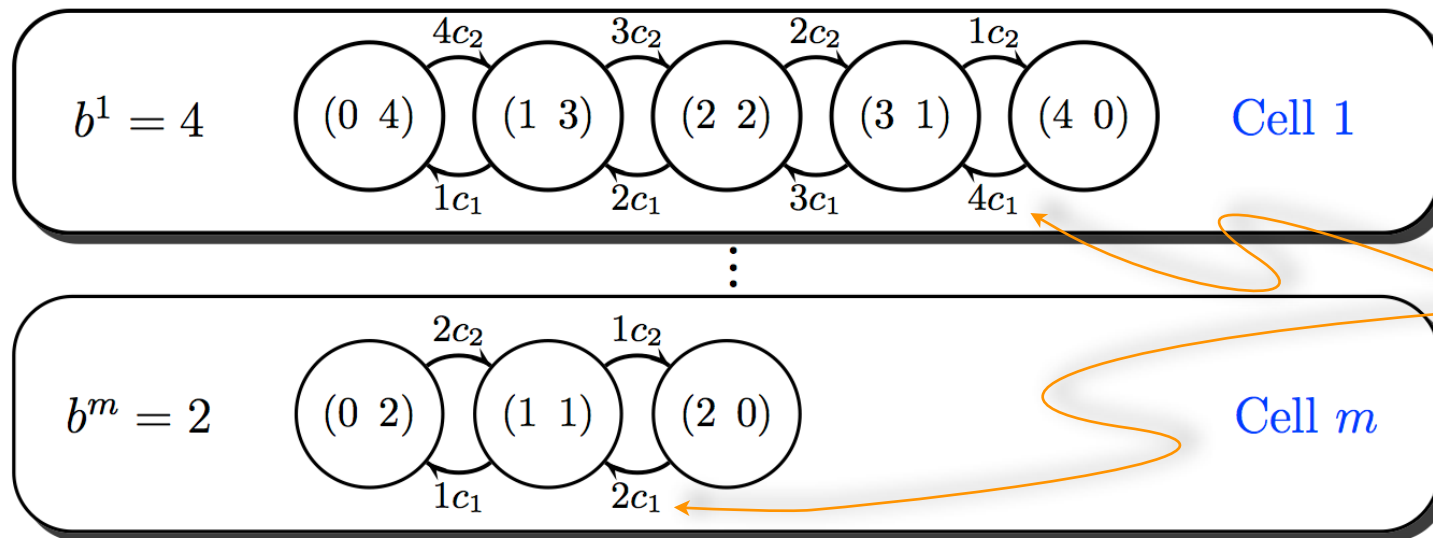
Illustrating the idea: variability in mass-conservation

Example



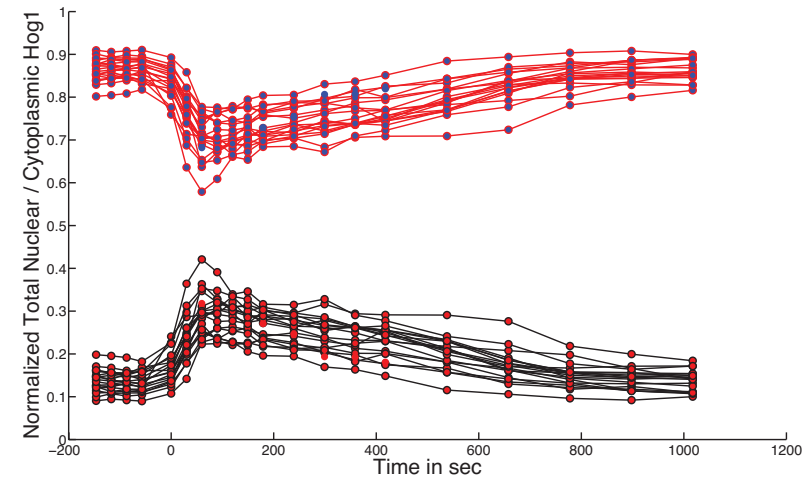
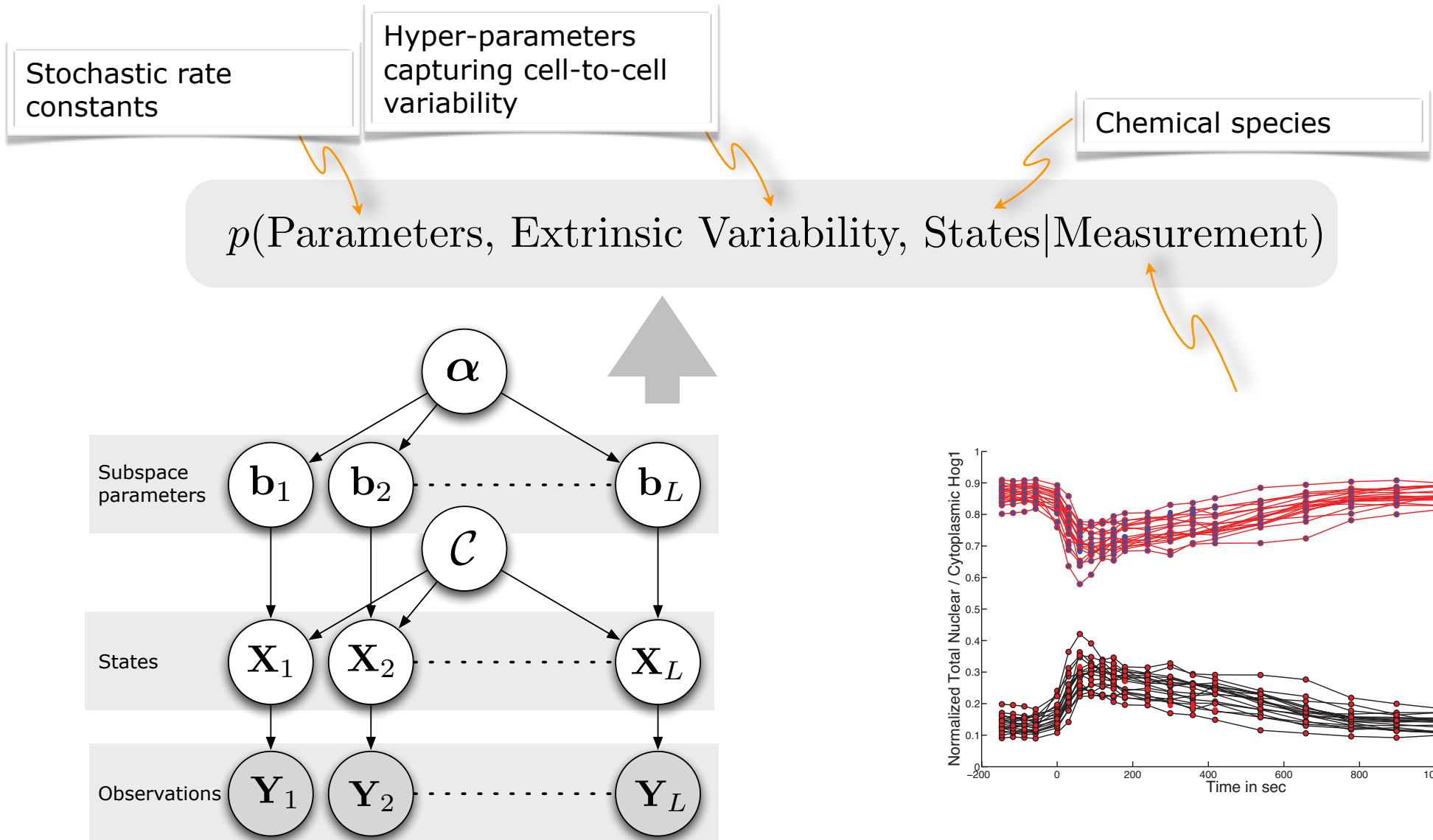
Mass-conservation $b = A + B$

Markov chains



■ **Goal:** Estimate common parameters by observing sample paths from a heterogeneous population of Markov-chains

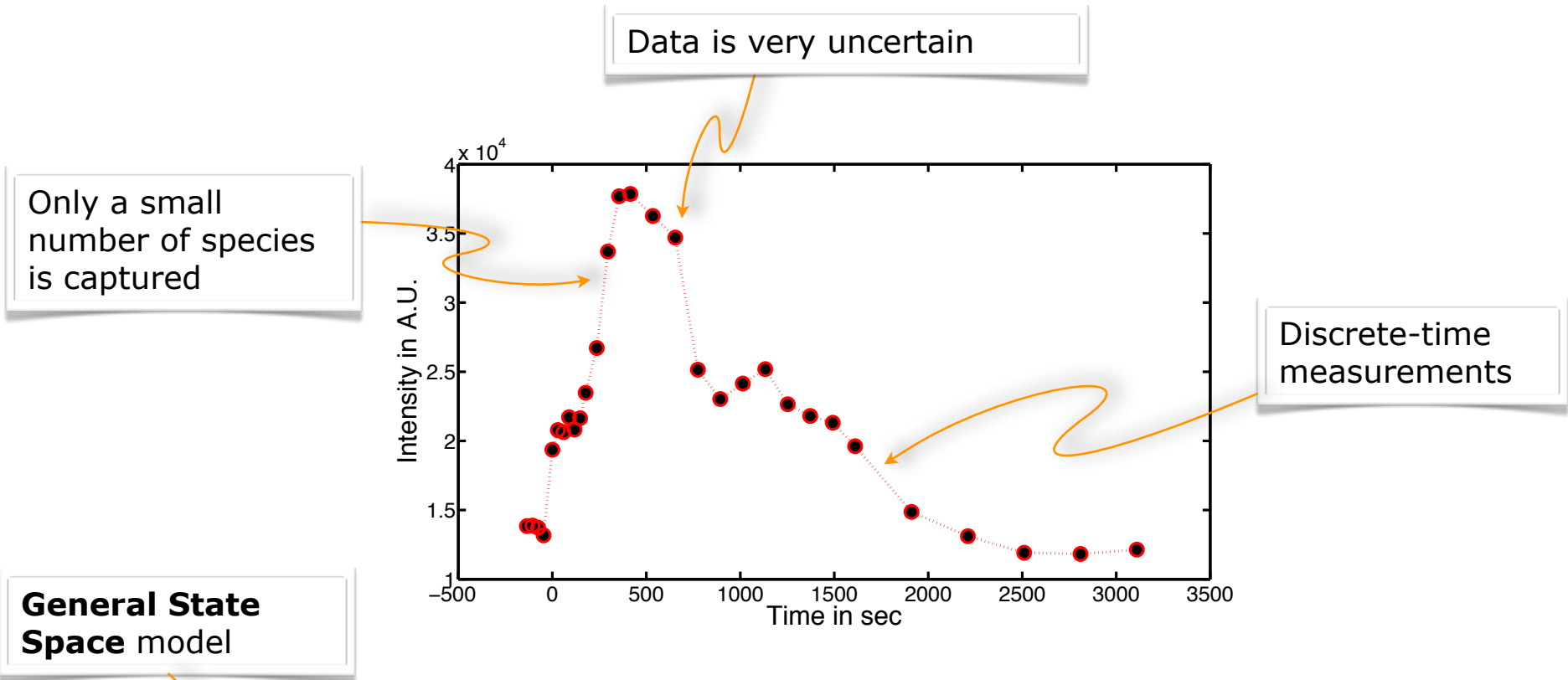
Overview: model calibration - statistical inference



$$p(\mathbf{c}, \alpha, \mathbf{X}_{[t_1, t_l]} | \mathbf{Y}(t_1), \dots, \mathbf{Y}(t_l)) = \int p(\mathbf{c}, \mathcal{B}, \alpha, \mathbf{X}_{[t_1, t_l]} | \mathbf{Y}(t_1), \dots, \mathbf{Y}(t_l)) d\mathcal{B}$$

Analytically intractable!

Setup - estimation of missing states



State transition kernel:

$$p(\mathbf{X}(t_l) | \mathbf{X}(t_{l-1}), \mathcal{C}) \leftarrow \text{CME}$$

Measurement likelihood:

$$p(\mathbf{Y}(t_l) | \mathbf{X}(t_l)) = \mathcal{N}(\mathbf{W}\mathbf{X}(t_l), \sigma^2)$$

■ One could use MCMC to sample from the state posterior

■ Infeasible if parameters are unknown

Prediction step:

$$p(\mathbf{X}(t_l), \mathcal{C} | \mathbf{Y}(t_1), \dots, \mathbf{Y}(t_{l-1})) = \int p(\mathbf{X}(t_l) | \mathbf{X}(t_{l-1}), \mathcal{C}) \times p(\mathbf{X}(t_{l-1}), \mathcal{C} | \mathbf{Y}(t_1), \dots, \mathbf{Y}(t_{l-1})) d\mathbf{X}(t_{l-1})$$

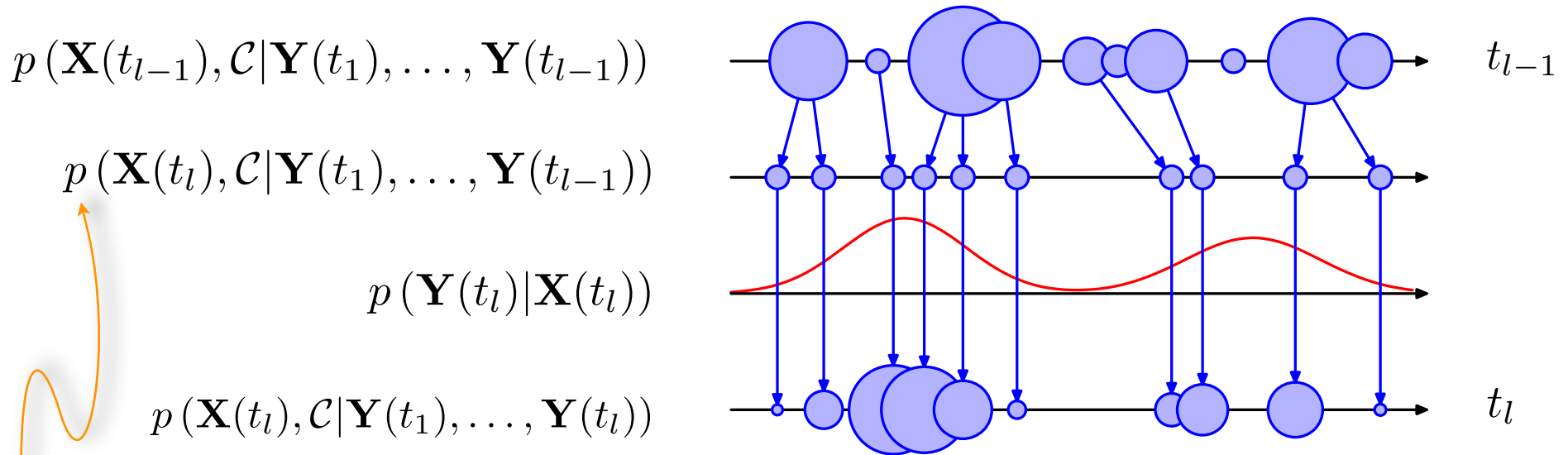
Correction step:

$$p(\mathbf{X}(t_l), \mathcal{C} | \mathbf{Y}(t_1), \dots, \mathbf{Y}(t_l)) \propto p(\mathbf{Y}(t_l) | \mathbf{X}(t_l)) \times p(\mathbf{X}(t_l), \mathcal{C} | \mathbf{Y}(t_1), \dots, \mathbf{Y}(t_{l-1}))$$

Bayesian Recursion
for sequential state
estimation

- Analytically tractable only for linear + fully Gaussian models: **Kalman filter**
- Integral can be approximated using sampling methods: **Sequential Monte Carlo**

Sequential Monte Carlo Sampling (sequential importance sampling)



Integral approximated using **importance sampling**

Particle approximation:

$$p(\mathbf{X}(t_l), \mathcal{C} | \mathbf{Y}(t_1), \dots, \mathbf{Y}(t_{l-1})) \approx \sum_{i=1}^P w^{(i)} p(\mathbf{X}(t_l) | \mathbf{X}^{(i)}(t_{l-1}), \mathcal{C})$$

Importance weights:

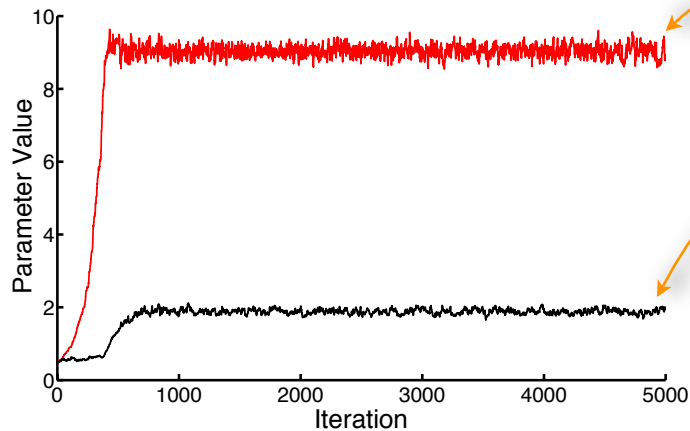
$$w^{(i)} \propto p(\mathbf{Y}(t_{l-1}) | \mathbf{X}^{(i)}(t_{l-1}))$$

Transition kernel as proposal distribution: **bootstrap filter** (Gillespie simulation)

○ Joint parameter & state estimation - video demo

<http://www.bison.ethz.ch/seqMC.mp4>

Markov chain Monte Carlo:



Chain with target posterior as it's stationary distribution

Detailed Balance Condition:

$$K(\mathcal{P}^{j+1}|\mathcal{P}^j)p(\mathcal{P}^j|\mathcal{Y}) = K(\mathcal{P}^j|\mathcal{P}^{j+1})p(\mathcal{P}^{j+1}|\mathcal{Y})$$

Transition kernel of the Markov chain

Metropolis-Hastings Sampler

Proposal density

Known from model

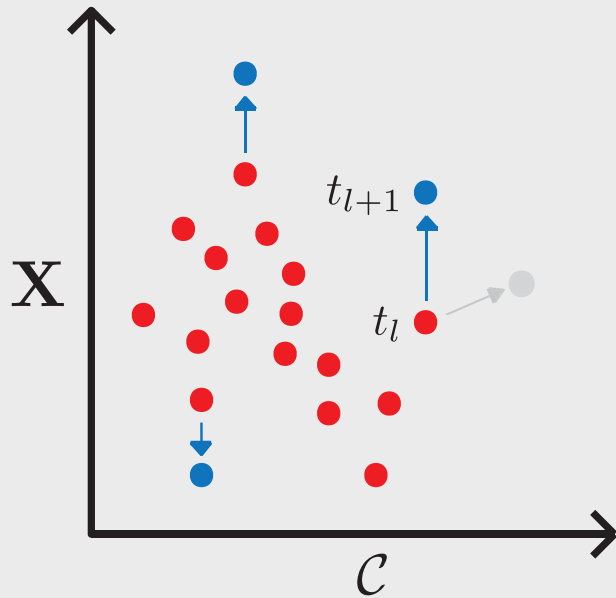
$$a = \min \left\{ 1, \frac{q(\mathcal{P}^j|\mathcal{P}^{j+1})p(\mathcal{P}^{j+1}|\mathcal{Y})}{q(\mathcal{P}^{j+1}|\mathcal{P}^j)p(\mathcal{P}^j|\mathcal{Y})} \right\}$$

Acceptance probability

M-H fulfills detailed balance:

$$\begin{aligned} K(\mathcal{P}^{j+1}|\mathcal{P}^j)p(\mathcal{P}^j|\mathcal{Y}) &= a \times q(\mathcal{P}^{j+1}|\mathcal{P}^j)p(\mathcal{P}^j|\mathcal{Y}) \\ &= \min \{ q(\mathcal{P}^{j+1}|\mathcal{P}^j)p(\mathcal{P}^j|\mathcal{Y}), q(\mathcal{P}^j|\mathcal{P}^{j+1})p(\mathcal{P}^{j+1}|\mathcal{Y}) \} \\ &= K(\mathcal{P}^j|\mathcal{P}^{j+1})p(\mathcal{P}^{j+1}|\mathcal{Y}) \end{aligned}$$

Sequential Monte Carlo sampling - MCMC moves



- Parameters cannot take values different from their initialization
- Particles degenerate!
- Additional MCMC moves can be used to diversify particles

Sample trajectory from the particle distribution and ignore corresponding parameter (**marginalization**)

Sample new parameter given the trajectory from Gamma

$$\{\mathbf{X}_{[t_1, t_l]}, \mathcal{C}\} \sim p(\mathbf{X}_{[t_1, t_l]} | \mathbf{Y}(t_1), \dots, \mathbf{Y}(t_l)) p(\mathcal{C} | \mathbf{X}_{[t_1, t_l]})$$

Still a valid sample from the target posterior!

Bootstrap filter for state & parameter estimation:

- 1: **for** $t_l \in \{t_2, \dots, t_L\}$ **do**
- 2: Resample particles according to their weights
- 3:
- 4: **for** each particle $i \in \{1, \dots, P\}$ **do**
- 5: **for** each rate constant $c_k^i \in \mathcal{C}^i$ **do**
- 6: Update parameter posterior (Γ -distribution)
- 7: Sample new c_k^i from posterior
- 8: **end for**
- 9:
- 10: Forward simulate path to next measurement time point using proposed parameter values
- 11:
- 12: Recompute particle weight
- 13: **end for**
- 14: Normalize particle weights
- 15: **end for**

Include MCMC step for parameters after particle resampling

Gillespie!

Measure "goodness" of simulated subpath

Must be a valid probability distribution

Bootstrap filter for state & parameters - multiple cells

```
1: for  $t_l \in \{t_2, \dots, t_L\}$  do
2:   Resample particles according to their weights
3:
4:   for each particle  $i \in \{1, \dots, P\}$  do
5:
6:     for each rate constant  $c_k^i \in \mathcal{C}^i$  do
7:       Update parameter posterior ( $\Gamma$ -distribution)
8:       Sample new  $c_k^i$  from posterior
9:     end for
10:
11:    for each cell  $m \in \{1, \dots, L\}$  do
12:      Update posterior over conservation constants (discrete density)
13:      Sample new conservation constant
14:    end for
15:
16:    Sample hyperparameters using M-H
17:
18:    Forward simulate path to next measurement time point using proposed
    parameter values
19:
20:    Recompute particle weight
21:  end for
22:  Normalize particle weights
23: end for
```

All cells are used to update the posterior!

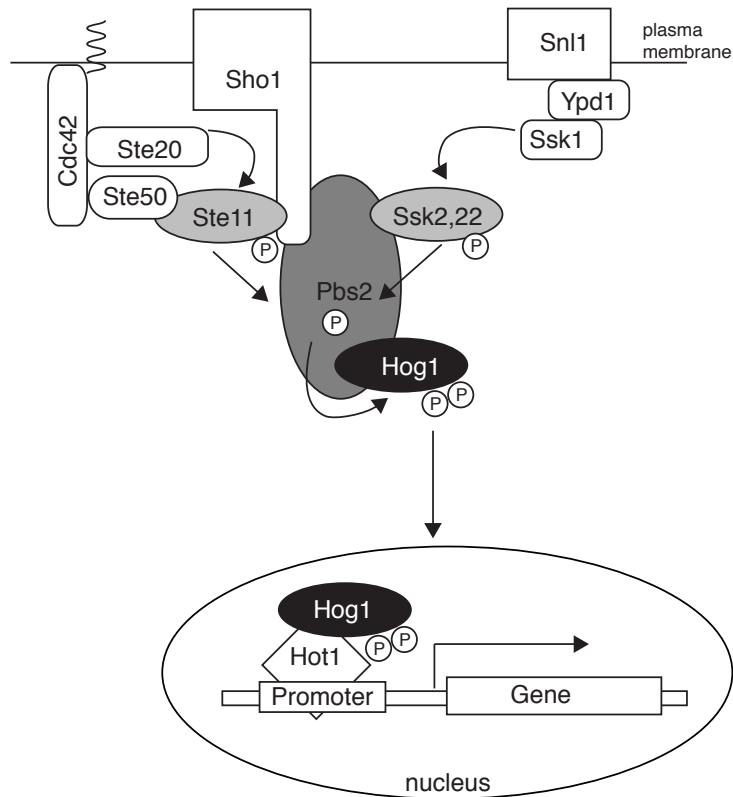
Additionally we sample the "extrinsic" variables - sufficient statistics

...and the statistics (extrinsic noise)

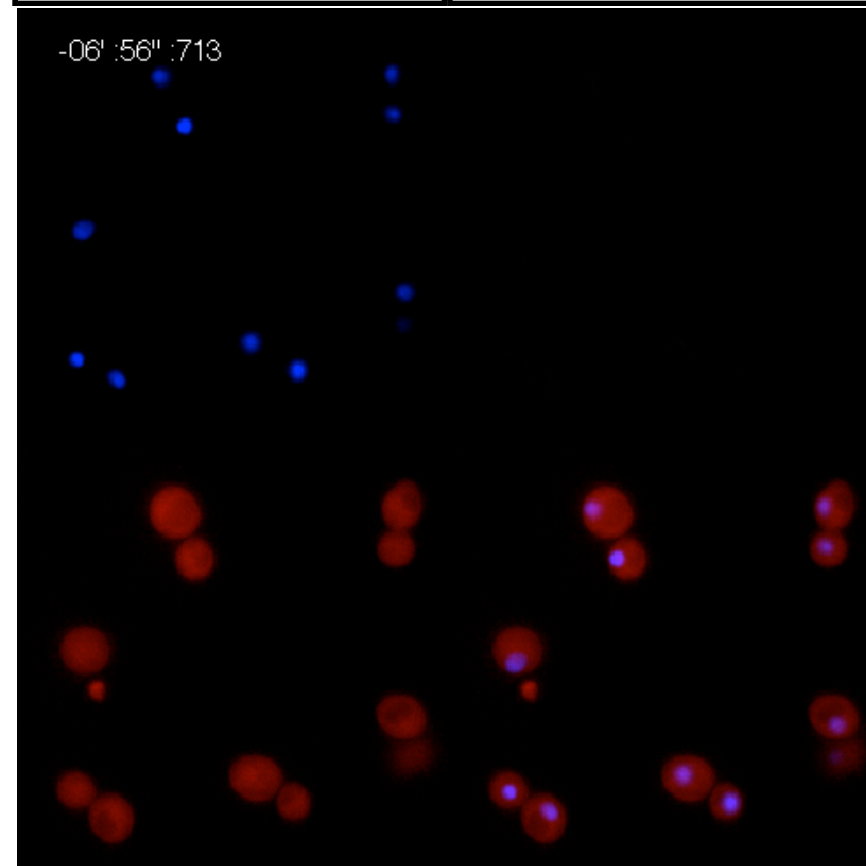
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case study: osmostress response in yeast

[Movie description]

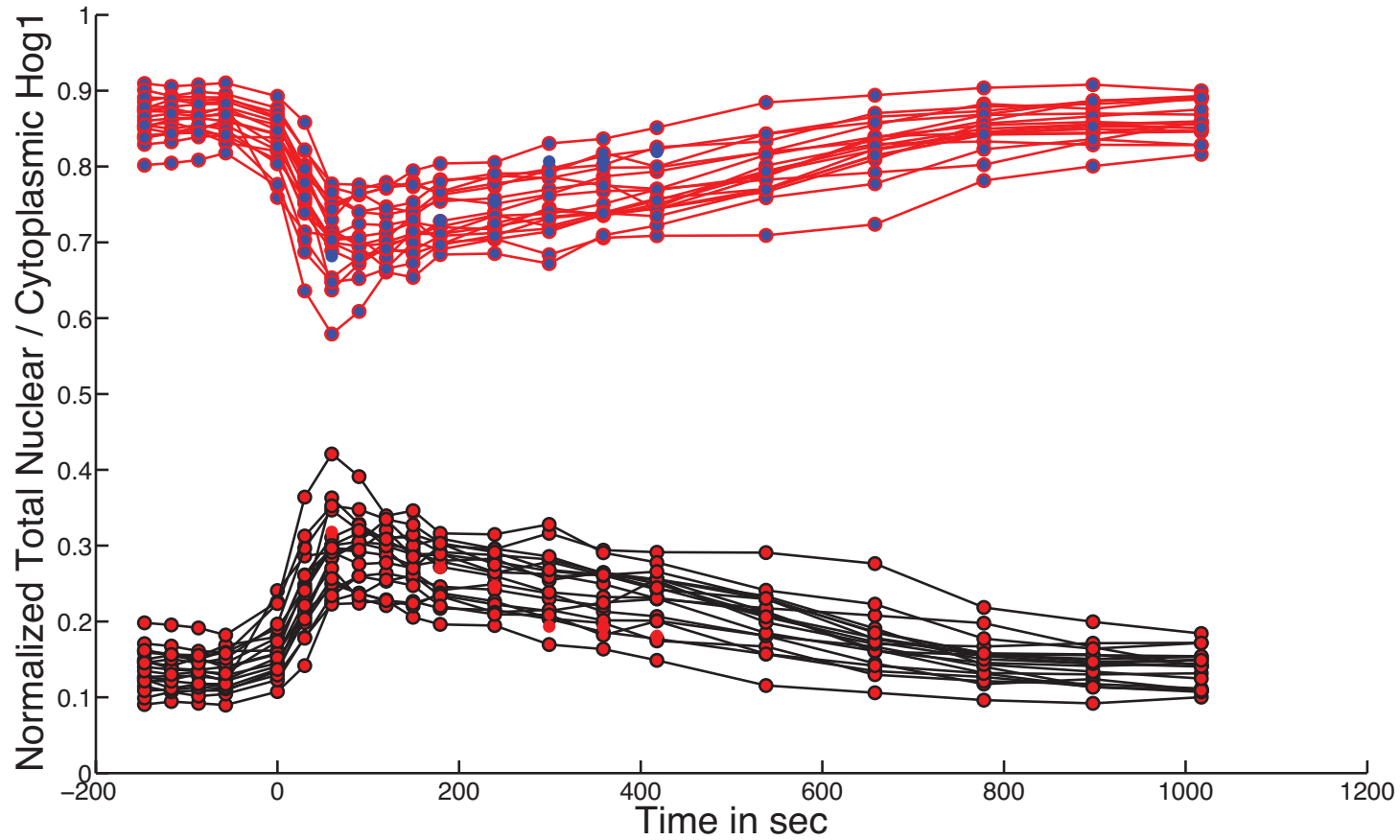


Position of nucleus	Expression of stress proteins
Abundance and location of phosphorylated Hog1 protein	Overlay of all channels

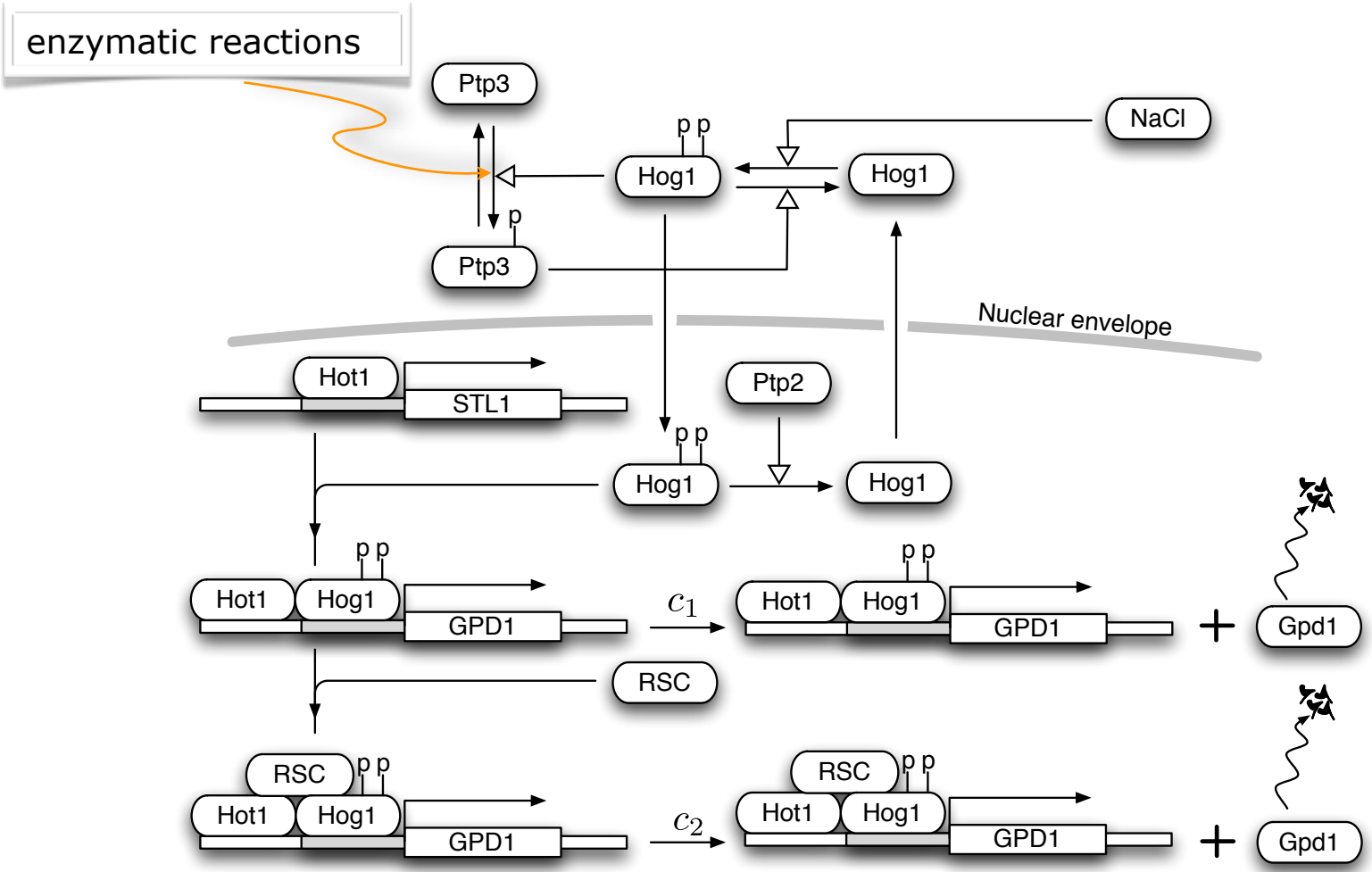


Relocation microscopy data: sample traces

Observables: total HOG proteins and nuclear HOG proteins
(and expression of reporter gene)

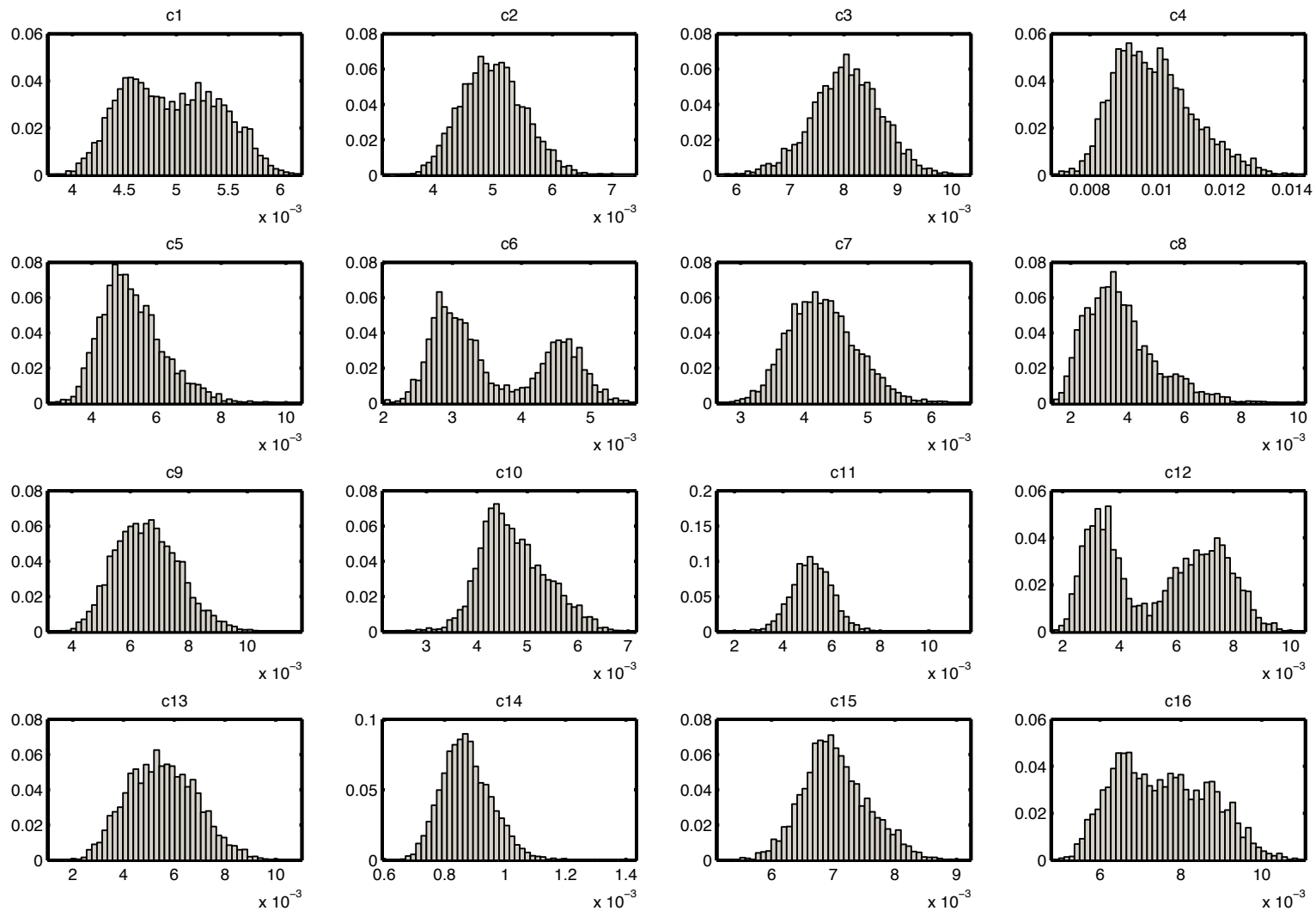


Simple signaling, shuttling and transcriptional model

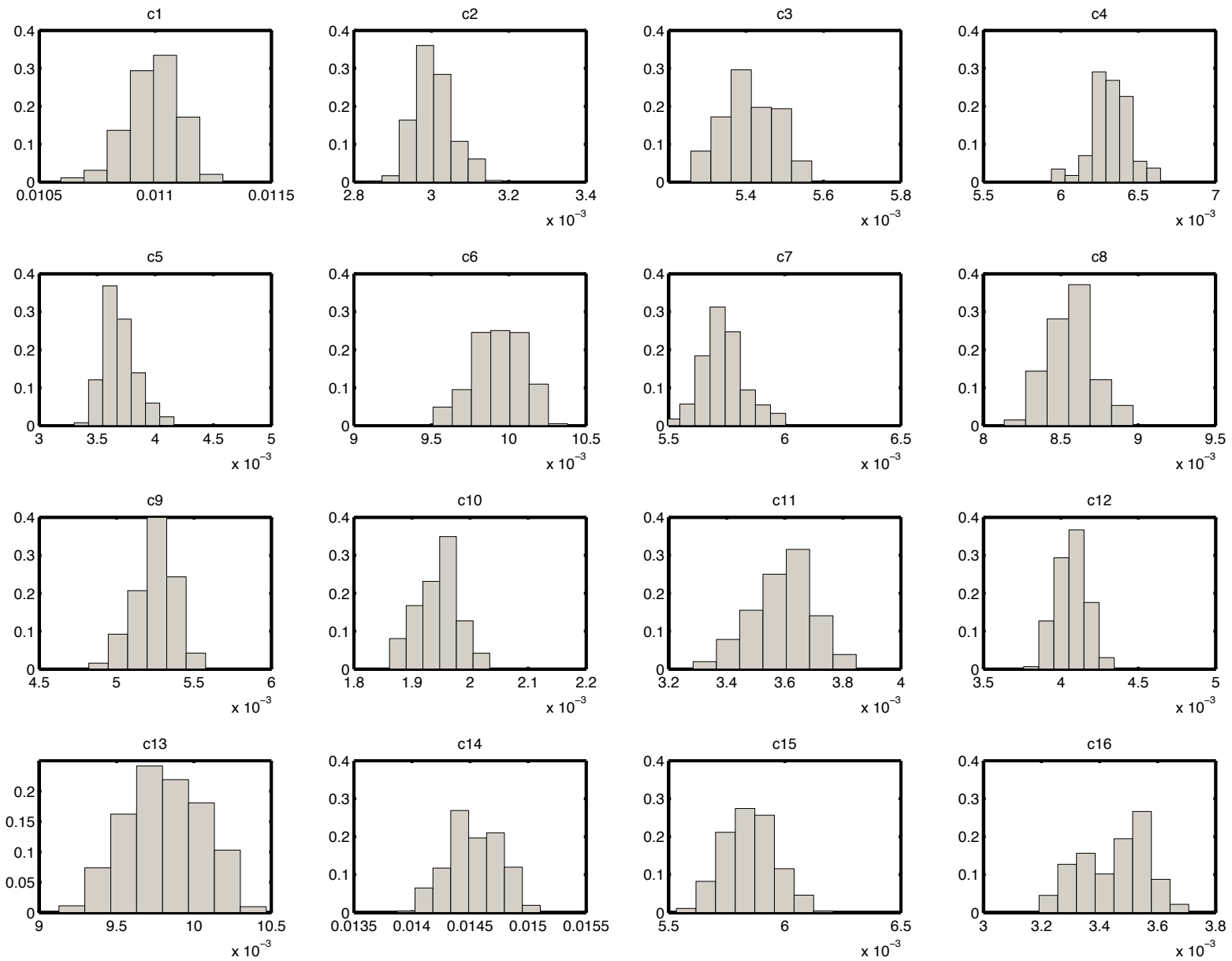


...11 states, 16 kinetic rate constants (with log-normal priors)

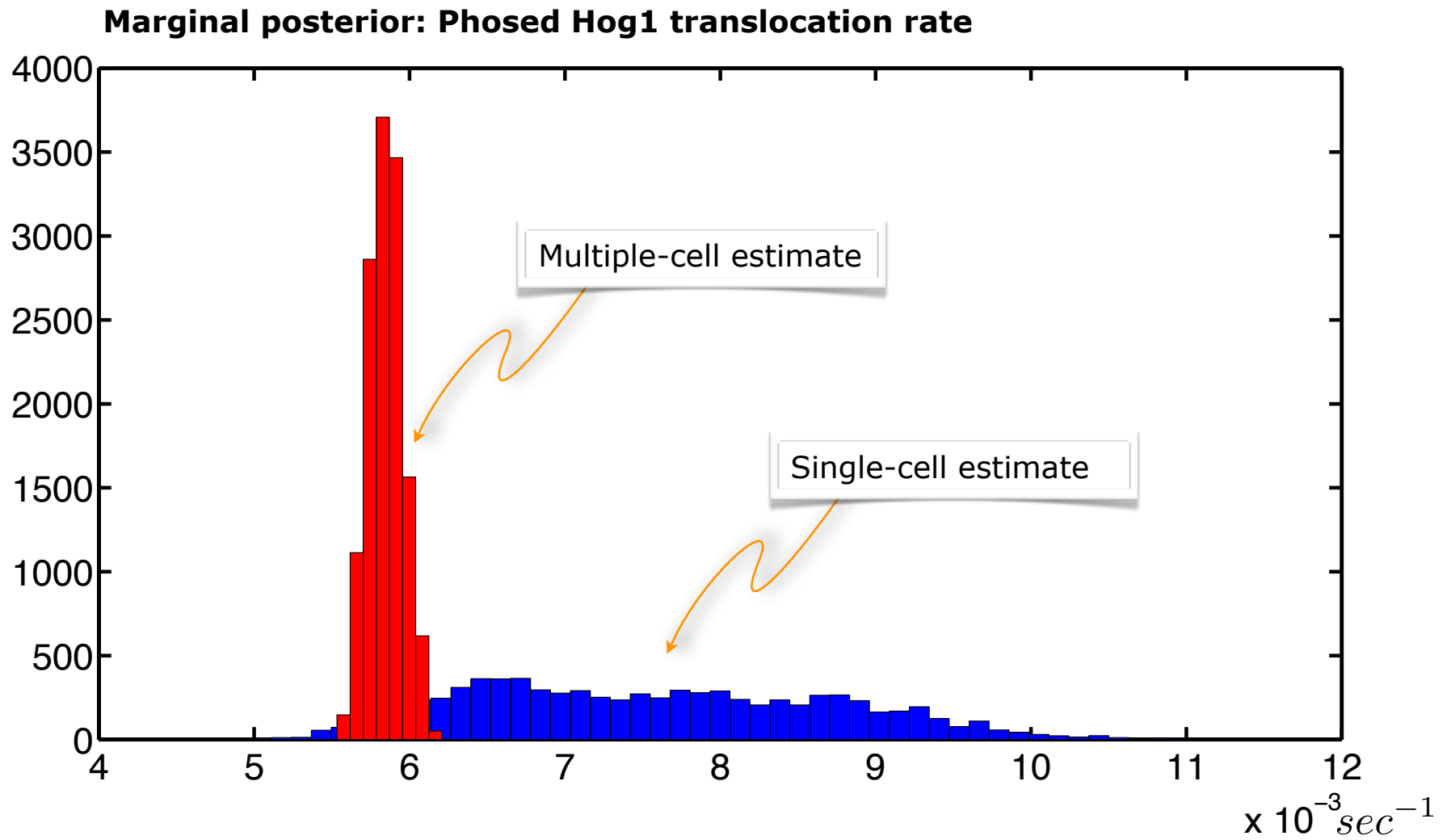
Estimation of all rate constants



Case study: multiple heterogeneous sample paths

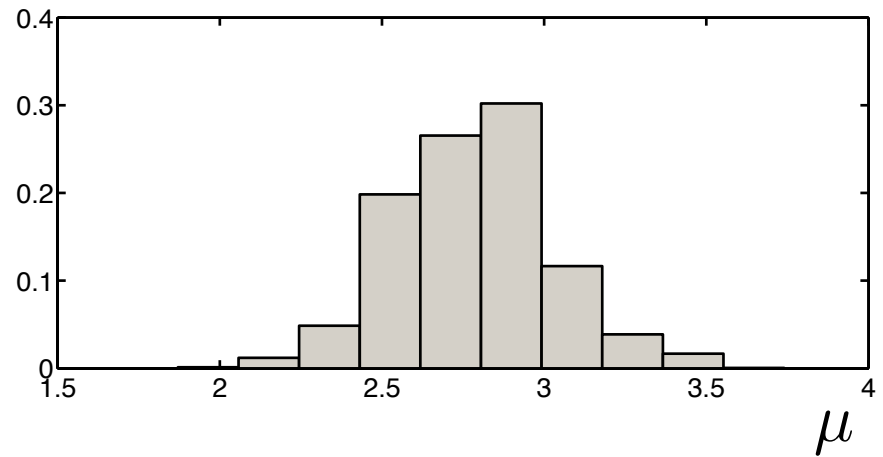
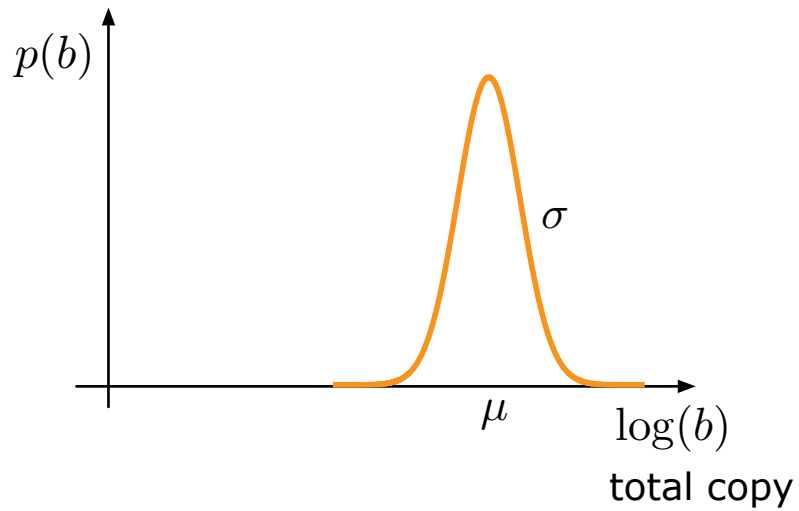
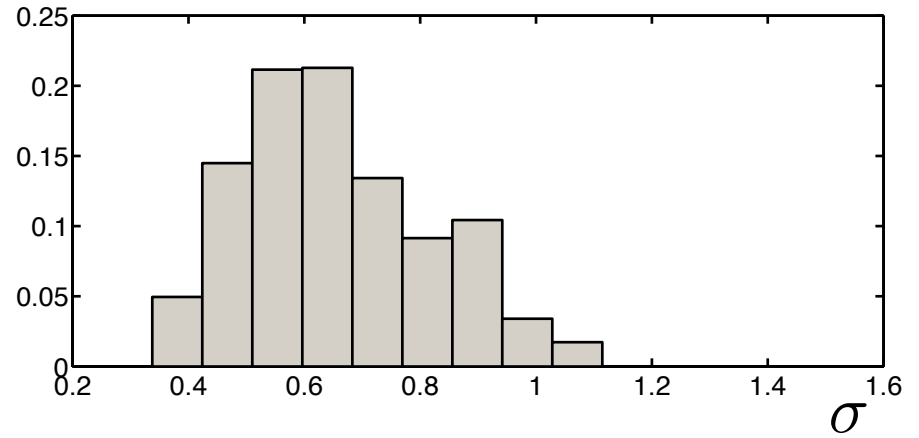
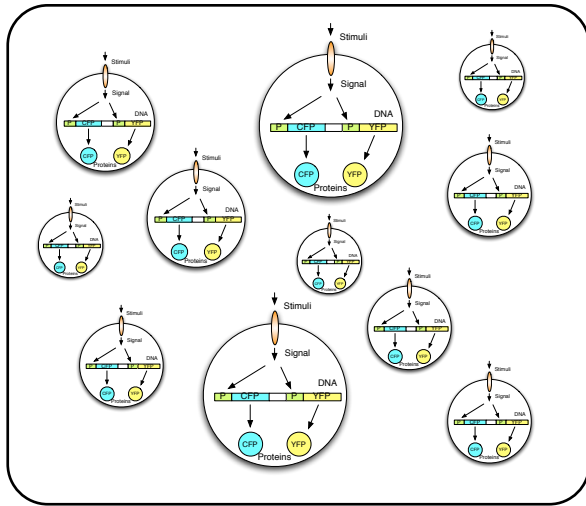


○ Confinement: multiple sample of heterogeneous population

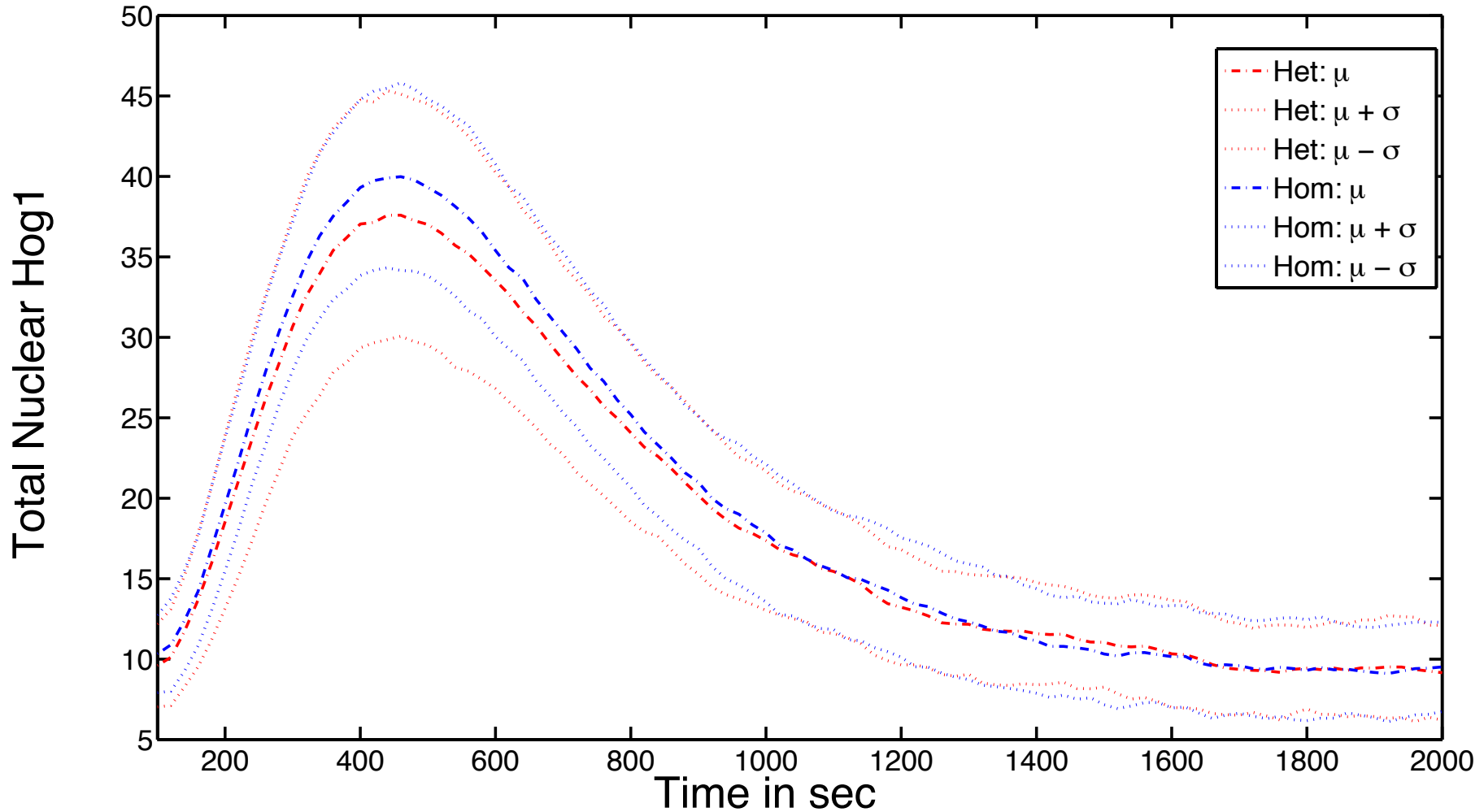


Distribution parameters for mass-conservations

cell-population



■ Artificial homogenization of cell-population - remaining variability intrinsic noise/stochastic kinetics.



- Single-cell technologies reveal **large cell-to-cell variability** - what are the important contributions to this variability?
- Complementary approach to capture cell-to-cell variability - variability in total **protein count or concentration**.
- Approach to estimate this contribution to the variability - allows **quantifying intrinsic component** (molecular noise).
- Applied to real-world data and situation - **low dimensional readout** and high measurement noise.
- ToDo: Better proposal density for SMC - **conditional Gillespie**.
- Arbitrary stress profiles - microfluidics

